Frequency flicker in ultra-stable quartz oscillators

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The frequency flicker of an oscillator, which appears as a $1/f^3$ line in the phase noise spectral density, and as a floor on the Allan variance plot, originates from two basic phenomena, namely: (1) the $1/f$ phase noise turned into $1/f$ frequency noise via the Leeson effect, and (2) the $1/f$ fluctuation of the resonator natural frequency. The discussion on which is the dominant effect, thus on how to improve the stability of the oscillator, has been going on for years without giving a clear answer. This article tackles the question by analyzing the phase noise spectrum of several commercial oscillators and laboratory prototypes, and demonstrates that the fluctuation of the resonator natural frequency is the dominant effect. The investigation method starts from reverse engineerizing the oscillator phase noise in order to show that if the Leeson effect was dominant, the resonator merit factor $Q$ would be too low as compared to the available technology.

I. INTRODUCTION AND SUMMARY

In the domain of ultra-stable quartz oscillators used in the most demanding applications, like space and atomic fountain clocks, we notice that the frequency flicker is often the most critical parameter. The required stability is sometimes in the upper $10^{-14}$ (Allan deviation) at 1–30 s so, which can only be achieved in the lower HF band (5–10 MHz), and after selection. In such cases, identifying the dominant flicker mechanism is far from being trivial. Whereas some authors strongly suggest that the amplifier noise can be the parameter that limit the frequency stability, rather than the flickering of the resonator natural frequency [1, 2], the general literature seems not to give a clear answer. This conclusion results from a set of selected articles, which includes the measurement of the frequency stability [3, 4] and the interpretation of the flicker noise of crystal resonators [5, 6]; the design fundamentals of the nowadays BVA resonators [7]; some pioneering works on the low-frequency noise in quartz oscillators [8, 9]; more recent articles focusing on specific design solutions for ultra-stable oscillators [10–14]; and, as a complement, a thorough review of the SiO$_2$ crystal for the resonator fabrication is found in [15]. Conversely, in everyday-life oscillators, which span from the low-cost XOs to the OCXOs used in telecommunications and instrumentation, the relative simplicity of the low-noise electronics required indicates that the frequency flicker is chiefly the $1/f$ fluctuation of the resonator.

In a previous work [16], now extended to more commercial products and laboratory prototypes, we have analyzed the phase noise spectrum of some oscillators, aiming at understanding the internal mechanisms and parameters. We look at the phase-noise spectrum from the right hand to the left, hence from the higher Fourier frequencies to the lower, matching theory, technology and physical insight. In this way we get information on the sustaining amplifier on the output buffer, on the Leeson effect and on the resonator.

In this article we first explain the phase noise mechanisms in amplifiers. Then we introduce the Leeson effect, which consists of the phase-to-frequency conversion of noise below the resonator cutoff (Leeson) frequency $f_L = \frac{v_0}{2\pi}$. Finally, we analyze the phase noise spectral density $S_\varphi(f)$ of a few oscillators. The conclusion that the resonator natural frequency is the main cause of frequency flickering is based on experimental facts. After taking away the effect of the output buffer, we calculate the frequency $f''_L$ at which the oscillator $f^{-3}$ line crosses the $f^{-1}$ line of the sustaining amplifier. Provisionally assuming that $f''_L$ is the the Leeson frequency, we observe that the resonator merit factor $Q_s = \frac{2\pi f''_L}{\nu_0}$ thereby calculated is far too low for a high-tech resonator. Conversely, under any reasonable assumption about the true merit factor, the Leeson effect is found at a frequency $f_L \ll f''_L$. Therefore the Leeson $f^{-3}$ line on the $S_\varphi(f)$ plot is well hidden below the resonator fluctuation.

II. PHASE NOISE FUNDAMENTALS

Let the quasi-perfect oscillator sinusoidal signal of frequency $\nu_0$

$$v(t) = V_0[1 + \alpha(t)]\cos[2\pi\nu_0 t + \varphi(t)].$$

(1)

where $\alpha(t)$ is the fractional amplitude noise, and $\varphi(t)$ is the phase noise. The AM noise is not essential to this work. The phase noise is best described in terms of $S_\varphi(f)$, i.e., the one-sided power spectral density of $\varphi(t)$, as a function of the Fourier frequency $f$. In addition to $f$, we use the angular frequency $\omega$ for both carrier-related frequencies ($\omega = 2\pi\nu$), and Fourier frequencies ($\omega = 2\pi f$) without need of introducing it, and the normalized frequency fluctuation $y = \frac{\nu - \nu_0}{\nu_0}$. The quantities $\nu$, $f$ and $y$ refer to one-sided trans-
forms, $\omega$ to two-sided transforms. Frequency fluctuations are described in terms of $S_{\nu}(f)$, related to $S_{\varphi}(f)$ by

$$ S_{\nu}(f) = \frac{f^2}{b_0} S_{\varphi}(f). $$

(2)

A model that has been found useful in describing the oscillator noise spectra is the power-law

$$ S_{\nu}(f) = \sum_{i=-2}^{2} h_i f^i \quad \Rightarrow \quad S_{\varphi}(f) = \sum_{i=-4}^{0} b_i f^i. \tag{3} $$

Our main concern is the frequency flickering term $b_{-3}f^{-3}$, which is related to the Allan variance by

$$ \sigma_{\nu}^2 = 2 \ln(2) h_{-1} = 2 \ln(2) \frac{b_{-3}}{b_0}, \tag{4} $$

classical, i.e., independent of the measurement time.

Finally, the general background on phase noise and frequency stability is available from numerous references, among which we prefer [17], [18], [19], and [20, Vol. 1, Chapter 2]. A IEEE standard is also available [21].

III. PHASE NOISE IN RF (AND MICROWAVE) AMPLIFIERS

a. White noise. The equivalent noise spectrum density at the amplifier input is $N = FK T_0$, where $F$ is the noise figure and $kT_0$ is the thermal energy. This type of noise is additive. In the presence of a carrier of power $P_0$, the phase noise spectral density is

$$ S_{\varphi}(f) = b_0 f^0 \quad \text{(constant)} \tag{5} $$

with

$$ b_0 = \frac{K T_0}{P_0}. \tag{6} $$

When amplifiers are cascaded, the noise contribution of each stage is divided by the gain of all the preceding stages (Friis formula [22]). Accordingly, in most practical cases the total noise is chiefly the noise of the first stage. Of course, this also holds for phase noise.

b. Flicker noise. Understanding the close-in noise starts from the bare observation that the output spectrum is of the white type—flat in a wide frequency range—when the carrier power is zero, and that noise shows up close to the carrier only when a sufficiently large carrier power is present at the amplifier output. The obvious consequence is that the close-in flickering results from a parametric effect by which the feed-forward flicker noise modulates the carrier in amplitude and phase.

The simplest way to understand the noise up-conversion is to model the amplifier signal as a nonlinear function truncated to the 2nd order

$$ v_o(t) = a_1 v_i(t) + a_2 v_i^2(t) + \ldots, \tag{7} $$

in which the complex input signal

$$ v_i(t) = V_i e^{j\omega_0 t} + n'(t) + jn''(t) \tag{8} $$

contains the carrier and the internally generated near-DC noise $n(t) = n'(t) + jn''(t)$. Rather than being an easy-to-identify voltage or current, $n(t)$ is an abstract random signal that also accounts for the efficiency of the modulation process. Combining (7) and (8) and selecting the terms close to the carrier frequency $\omega_0$, we get

$$ v_o(t) = V_i \left\{ a_1 + 2a_2 |n'(t) + jn''(t)| \right\} e^{j\omega_0 t}. \tag{9} $$

Hence, the random fluctuations are

$$ \alpha(t) = 2 \frac{a_2}{a_1} n'(t) \quad \text{and} \quad \varphi(t) = 2 \frac{a_2}{a_1} n''(t). \tag{10} $$

Deriving Eq. (10), the statistical properties of $n'(t)$ and $n''(t)$ are not affected by the carrier power. This accounts for the experimental observation that the amplifier phase noise given in rad$^2$/Hz is about independent of power in a wide range [23–25]. Thus

$$ S_{\varphi}(f) = b_{-1} f^{-1} \quad b_{-1} \approx \text{constant}. \tag{11} $$

Of course, some dependence on $P_0$ remains. We ascribe it to terms of order higher than 2 in (7), and to the effect of the large signal regime on the DC bias. In the case of bipolar amplifiers used in HF/VHF amplifiers, $b_{-1}$ is in the range of 10–12 to 10–14 rad$^2$/Hz ($–120$ to $–140$ dBrad$^2$/Hz).

When $m$ amplifiers are cascaded, the Friis formula does not apply. Instead, the phase noise barely adds

$$ (b_{-1})_{\text{cascade}} = \sum_{i=1}^{m} (b_{-1})_i. \tag{12} $$

This occurs because the $1/f$ phase noise is about independent of power. Of course, the amplifiers are supposed independent.
A – Oscillator loop

B – Phase–space equivalent

FIG. 2: Oscillator model and its phase-space equivalent. For the sake of simplicity all the dependence on \( s \) is moved to \( \beta(s) \), hence the gain \( A \) is assumed constant. The scheme emphasizes the amplifier phase noise. Amplitude noise is not considered.

c. Phase noise spectrum. Combining white noise [Eq. (5)] and flicker noise [Eq. (11)], there results the spectral density \( S_\phi(f) \) shown in Fig. 1. It is important to understand that the white noise term \( b_0f_0^0 \) depends on the carrier power \( P_0 \), while the flicker term \( b_-1f_-1^0 \) does not. Accordingly, the corner frequency \( f_c \) at which \( b_-1f_-1^0 = b_0 \) is a function of \( P_0 \), thus \( f_c \) should not be used to describe noise. The parameters \( b_-1 \), \( F \), and \( P_0 \) should be used instead.

IV. PHASE NOISE IN OSCILLATORS

A. The Leeson effect

Figure 2 shows a model for the feedback oscillator, and its equivalent in the phase space. All signals are the Laplace transform of the time-domain quantities, as a function of the complex frequency \( s = \sigma + j\omega \). The oscillator transfer function is derived from Fig. 2 A according to the basic rules of linear systems

\[
H(s) = \frac{1}{\beta(s)} \frac{1}{1 - \frac{A}{A_s(s)} - 1} = \frac{A}{1 - A_s(s)} \tag{13}
\]

Stationary oscillation occurs at the angular frequency \( \omega_0 \) at which \( A\beta(j\omega) = 1 \), thus \( |A\beta(j\omega)| = 1 \) and \( \arg[A\beta(j\omega)] = 0 \). This is known as the Barkhausen condition for oscillation. At \( s = j\omega_0 \) the denominator of \( H(s) \) is zero, hence oscillation is sustained with zero input signal. Oscillation starts from noise or from the switch-on transient if \( \Re[{A\beta(s)}]_{s=j\omega_0} > 1 \) (yet only slightly greater than 1 for practical reasons). When the oscillation reaches a threshold amplitude, the loop gain is reduced to 1 by saturation. The excess power is pushed into harmonics multiple of \( \omega_0 \), and blocked by the resonator. For this reason, at \( \omega_0 \) the oscillator operates in quasi-linear regime.

In most quartz oscillators, the sustaining amplifier takes the form of a negative resistance that compensates for the resonator loss. Such negative resistance is interpreted (and implemented) as a transconductance amplifier that senses the voltage across the input and feeds a current back to it. Therefore, the negative-resistance oscillator loop is fully equivalent to that shown in Fig. 2.

In 1966, D. B. Leeson [26] suggested that the oscillator phase noise is described by

\[
S_\phi(f) = \left[1 + \frac{1}{f^2} \frac{\nu_0^2}{4Q^2}\right] S_\psi(f) \quad \text{(Leeson),} \tag{14}
\]

This formula calls for the phase-space representation of Fig. 2 B, which deserves the following comments.

The Laplace transform of the phase of a sinusoid is probably the most common mathematical tool in the domain of PLLs [27–30]. Yet it is unusual in the analysis of oscillators. The phase-space representation is interesting in that the phase noise turns into additive noise, and the system becomes linear. The noise-free amplifier barely repeats the input phase, for it shows a gain exactly equal to one, with no error. The resonator transfer function, i.e., the Laplace transform of the impulse response, is

\[
B(s) = \frac{1}{1 + s\tau} \quad \tau = \frac{2Q}{\omega_0}. \tag{15}
\]

The inverse time constant is the low-pass cutoff angular frequency of the resonator

\[
\omega_L = \frac{1}{\tau} = \frac{\omega_0}{2Q}. \tag{16}
\]

The corresponding frequency

\[
f_L = \frac{\omega_L}{2\pi} = \frac{1}{2\pi\tau} = \frac{\nu_0}{2Q} \tag{17}
\]

is known as the Leeson frequency. Equation (15) is proved in two steps:

1. Feed a Heaviside step function \( \kappa U(t) \) in the argument of the resonator input sinusoid. The latter becomes \( \cos(\omega_0t + \kappa U(t)) \).

2. Linearize the system for \( \kappa \to 0 \). This is correct in low phase noise conditions, which is certainly our case. Accordingly, the input signal becomes \( \cos(\omega_0t) - \kappa \sin(\omega_0t) U(t) \).
Leeson effect

Calculate the Laplace transform of the step response, and use the property that the Laplace transform maps the time-domain derivative into a multiplication by the complex frequency s. The Dirac function δ(t) is the derivative of U(t).

The full mathematical details of the proof are available in [16, Chapter 3].

Applying the basic rules of linear systems to Fig. 2 B, we find the transfer function

\[ H(s) = \frac{\Phi(s)}{\Psi(s)} = \frac{1}{1 - B(s)} = \frac{1 + s\tau}{s\tau}, \quad (18) \]

thus

\[ |H(j\omega)|^2 = \frac{1 + \omega^2\tau^2}{\omega^2 + 2\omega \tau + \tau^2}. \quad (19) \]

The Leeson formula (14) derives from Eq. (19) by replacing

\[ \omega = 2\pi f \quad \text{and} \quad \tau = \frac{Q}{\pi v_0}. \quad (20) \]

The transfer function \( H(s) \) has a pole in the origin (pure integrator), which explains the Leeson effect, i.e., the phase-to-frequency noise conversion at low Fourier frequencies. At high Fourier frequencies it holds that \( H(j\omega) = 1 \). In this region, the oscillator noise is barely the noise of the sustaining amplifier.

The amplifier phase noise spectrum contains flicker and white noise, i.e., \( S_\psi(f) = (b_{-1})_{\text{ampli}} f^{-1} + (b_0)_{\text{ampli}} \). Feeding such \( S_\psi(f) \) into the Leeson formula (14), the oscillator \( S_\phi(f) \) can only be one of those shown in Fig. 3. Denoting with \( f_c \) the corner frequency at which flicker noise equals white noise, we often find \( f_L < f_c \) in HF/VHF high-Q oscillators, and \( f_L > f_c \) in microwave oscillators. In ultra-stable HF quartz oscillators (5–10 MHz), the spectrum is always of the type A (\( f_L < f_c \)).

A – High Q, low \( v_0 \) (xtal) B – Low Q, high \( v_0 \) (microwave)

\[ S_\phi(f) \]

\[ S_\psi(f) \]

Leeson effect

FIG. 3: Oscillator phase noise, not accounting for the output buffer.

3. Calculate the Laplace transform of the step response, and use the property that the Laplace transform maps the time-domain derivative into a multiplication by the complex frequency s. The Dirac function δ(t) is the derivative of U(t).

The phase noise \( S_\psi(f) \) of the output buffer barely adds to the oscillator phase noise

\[ S_\psi(f) = \left[ 1 + \frac{\nu_0^2}{4Q^2} \right] S_\phi(f) + S_\psi(f). \quad (21) \]

This a consequence of the flicker noise mechanism explained Section III 0 b, and inherent in the model of Fig. 2 B.

C. Resonator stability

The oscillator frequency follows the random fluctuation of the resonator natural frequency. However complex or tedious the formal proof for this statement can be, the experimentalist is familiar with the fact that the quartz oscillator can be frequency-modulated by a signal of frequency far higher than the Leeson frequency. For example, a 5 MHz oscillator based on a \( Q = 2 \times 10^6 \) resonator shows a Leeson frequency of 1.25 Hz (see Table I), while it can be modulated by a signal in the kHz region. Additionally, as a matter of fact, the modulation index does not change law from below to beyond the Leeson frequency. This occurs because the modulation input acts on a varactor in series to the quartz, whose capacitance is a part of the motional parameters.

D. Other effects

The sustaining amplifier of a quartz oscillator always includes some kind of feedback; often the feedback is used to implement a negative resistance that makes the resonator oscillator by nulling its internal resistance. The input admittance \( Y_i \) seen at the amplifier input can be represented as

\[ Y_i = Y_i^{(v)} + Y_i^{(r)}, \quad (22) \]

that is, the sum of a virtual term (v) plus a real term (r). The difference between ‘virtual’ and ‘real’ is that in the case of the virtual admittance the input current flows into the feedback path, while in the case of the real admittance the input current flows through a grounded dipole. This is exactly the same concept of virtual impedance routinely used in the domain of analog circuits [31, Chapter 1]. The admittance \( Y_i^{(r)} \) also includes the the effect of the pulling capacitance in series to the resonator, and the stray capacitances of the electrical layout. As a consequence, the fluctuation \( \delta Y_i^{(v)} \) is already accounted for in the amplifier noise, hence in the model of Fig. 2, while the fluctuation \( \delta Y_i^{(r)} \) is not. On the other hand, \( Y_i^{(r)} \) interacts with the resonator parameters, thus \( \delta Y_i^{(r)} \) yields frequency fluctuations not included in the Leeson effect.
We start from the spectrum, measured or taken from the oscillator. At first sight, the cutoff frequency is given by the term

$$S(f) = \frac{P_0}{Q_0^2 f^4}.$$  

This looks like that of Fig. 4 A, but the hard assumption is made in our analysis, that the buffer contributes 3/4 of the total noise, and that sustaining amplifier, rather than in the buffer. Thus, we assume that the buffer contributes 3/4 of the total noise, and that sustaining amplifier, rather than in the buffer.

Owing to the Leeson effect, a wise designer will spend the lowest-noise technology in the sustaining amplifier and of the output buffer, which will spend the lowest-noise technology in the sustaining amplifier, rather than in the buffer. Thus, we assume that the buffer contributes 3/4 of the total noise, and that sustaining amplifier contributes 1/4 (−6 dB). Accordingly, we plot the line $b_{-3} f^{-3}$ in Fig. 4B, 6 dB below the total flicker.

After taking away the buffer noise, the continuation of the $b_{-3} f^{-3}$ line meets the $b_{-1} f^{-1}$ line at $f = f_L''$. The latter is a new candidate for the Leeson frequency. Feeding $f_L''$ into Eq. (17), we calculate the resonator merit factor $Q_s$ (the subscript $s$ stands for ‘spectrum’)

$$Q_s = \frac{\nu_0}{2f_L''}.$$  

FIG. 4: Interpretation of the oscillator phase noise.

The interpretation method is shown in Fig. 4, and discussed below.

1. We start from the spectrum, measured or taken from the oscillator specifications. The first step is to remove the residual of the mains (50 or 60 Hz and multiples) and other stray signals, and to fit the spectrum with the power-law [Eq. (3)]. This process is called parametric estimation of the spectrum. With a pinch of experience, sliding old-fashion squares on a A4-size plot gives unexpectedly good results. Otherwise, the mathematical methods explained in [38, 39] are useful. After this, the spectrum looks like that of Fig. 4 A.

2. The term $b_0 f^0$ is chiefly due to the sustaining amplifier, hence the amplifier input power can be calculated using Eq. (6)

$$P_0 = \frac{F k T_0}{b_0}.$$  

In the absence of information, it is wise to take $F = 1.26$ (1 dB). To the extent of our analysis, estimating $P_0$ is only a check of plausibility.

3. Feeding the oscillator $b_{-3}$ term into Eq. (4), we calculate the floor of the Allan deviation $\sigma_y$.

4. At first sight, the cutoff frequency $f_L'$ (Fig. 4 A) can be taken for the Leeson frequency because there the slope changes from $f^{-3}$ to $f^{-1}$. Yet the term $b_{-1} f^{-1}$ contains the flicker of the sustaining amplifier and of the output buffer, which add [Equations (12) and (21)]. For this reason, $f_L'$ can not be the Leeson frequency.

5. Actual oscillators have 2–4 buffer stages, the main purpose of which is to isolate the feedback loop from the environment in order to ensure frequency stability and to prevent injection locking. Owing to the Leeson effect, a wise designer will spend the lowest-noise technology in the sustaining amplifier, rather than in the buffer. Thus, we assume that the buffer contributes 3/4 of the total noise, and that sustaining amplifier contributes 1/4 (−6 dB). Accordingly, we plot the line $b_{-1} f^{-1}$ in Fig. 4B, 6 dB below the total flicker.

6. After taking away the buffer noise, the continuation of the $b_{-3} f^{-3}$ line meets the $b_{-1} f^{-1}$ line at $f = f_L''$. The latter is a new candidate for the Leeson frequency. Feeding $f_L''$ into Eq. (17), we calculate the resonator merit factor $Q_s$ (the subscript $s$ stands for ‘spectrum’)
TABLE I: Estimated Parameters of some Ultra-Stable Oscillators.

<table>
<thead>
<tr>
<th>Oscillator</th>
<th>ν₀</th>
<th>(b₋₃)ₜₒₜ</th>
<th>(b₋₁)ₜₒₜ</th>
<th>(b₋₁)ₐₚₜ</th>
<th>f₀'</th>
<th>f₀''</th>
<th>Qₜ</th>
<th>Qₛ</th>
<th>fₐ</th>
<th>(b₋₃)ₐₛₜ</th>
<th>R</th>
<th>Note</th>
<th>References</th>
</tr>
</thead>
<tbody>
<tr>
<td>Oscilloquartz 8607</td>
<td>5</td>
<td>−124.0</td>
<td>−131.0</td>
<td>−137.0</td>
<td>2.24</td>
<td>4.5</td>
<td>5.6×10⁵</td>
<td>1.8×10⁶</td>
<td>1.4</td>
<td>−134.1</td>
<td>10.1</td>
<td>(1)</td>
<td>[14, 32]</td>
</tr>
<tr>
<td>FEMTO-ST LD protot.</td>
<td>10</td>
<td>−116.6</td>
<td>−130.0</td>
<td>−136.0</td>
<td>4.7</td>
<td>9.3</td>
<td>5.4×10⁵</td>
<td>1.5×10⁶</td>
<td>4.3</td>
<td>−123.2</td>
<td>6.6</td>
<td>(3)</td>
<td>[34]</td>
</tr>
<tr>
<td>Agilent 10811</td>
<td>10</td>
<td>−103.0</td>
<td>−131.0</td>
<td>−137.0</td>
<td>25</td>
<td>50</td>
<td>1×10⁵</td>
<td>7×10⁵</td>
<td>7.1</td>
<td>−119.9</td>
<td>16.9</td>
<td>(4)</td>
<td>[35]</td>
</tr>
<tr>
<td>Wenzel 501-04623</td>
<td>100</td>
<td>−67.0</td>
<td>−132?</td>
<td>−138?</td>
<td>1800</td>
<td>3500</td>
<td>1.4×10⁴</td>
<td>8×10⁴</td>
<td>625</td>
<td>−79.1</td>
<td>15.1</td>
<td>(6)</td>
<td>[37]</td>
</tr>
</tbody>
</table>

Notes
(1) Data are from specifications, full options about low noise and high stability.
(2) Measured by CMAC on a sample. CMAC confirmed that 2×10⁶ < Q < 2.2×10⁶ in actual conditions. See Fig. 5.
(3) LD cut, built and measured in our lab, yet by a different team. All design parameters are known, hence Qₜ.
(4) Measured by Hewlett Packard (now Agilent) on a sample.
(5) Implements a bridge scheme for the degeneration of the amplifier noise. Same resonator of the Agilent 10811.
(6) Data are from specifications. See Fig. 7.

7. Technology suggests a merit factor Qₜ (the subscript t stands for ‘technology’) significantly larger than Qₛ, even in actual load conditions. Feeding Qₜ into Eq. (17), we calculate fₐ based on the actual merit factor

\[ fₐ = \frac{\nu₀}{2Qₜ} \]  

as shown in Fig. 4 C. There follows a phase noise term (b₋₃)ₐₛₜ, which account for the Leeson effect alone.

8. Given Qₜ ≫ Qₛ, thus fₐ < f₀'', the Leeson effect is hidden. Consequently, the oscillator f⁻³ phase noise is chiefly due to the fluctuation of the resonator natural frequency.

We introduce the stability ratio R, defined as

\[ R = \frac{(σᵧ)ₐₛₜ}{(σᵧ)ₐₛₜ} \]  

and related to the other oscillator parameters by

\[ R = \sqrt{\frac{(b₋₃)ₜₒₜ}{(b₋₃)ₐₛₜ}} = \frac{Qₜ}{Qₛ} \frac{f₀''}{fₐ} \]  

This can be demonstrated from the b₋₃ term of the Leeson formula (14), using Equations (4) and (17). The parameter R states how bad is the actual oscillator, as compared to the same oscillator governed only by the Leeson effect, with the resonator fluctuations removed. Thus, R = 1 (0 dB) indicates that the oscillator f⁻³ phase noise comes from the Leeson effect. Equal contribution of resonator and Leeson effect yield R = √2 (3 dB), while R ≫ √2 is found when resonator instability is the main cause of f⁻³ phase noise. In all cases we have analyzed, discussed in the next Section, we find R of the order of 10 dB, with a minimum of 6.6 dB. This means that the Leeson effect is hidden below the frequency fluctuation of the resonator.

Coming back to the estimation of the 1/f noise of the sustaining amplifier it is to be remarked that if the 1/f noise of this is lower than 1/4 of the total flicker, f₀'' is further pushed on the right hand on Fig. 4 B-C, which reinforces the conclusion that the resonator is the main cause of frequency fluctuation.

VI. EXPERIMENTAL DATA AND DISCUSSION

Figure 5 shows the phase noise spectrum of a 5 MHz oscillator, out of a small series intended as the flywheel for the space Cesium fountain clock Pharao [40, 41]. On this plot, the reader can follow the interpretation process explained in Section V, and illustrated in Fig. 4. Guessing on technology, the merit factor was estimated to be 2×10⁶. Afterwards, the manufacturer confirmed [42] that Qₜ is between 2×10⁶ and 2.2×10⁶ in actual load conditions for that series of oscillators,
and that the flicker noise of the sustaining amplifier is less than 1/4 (−6 dB) of the total flickering. This validates our conclusions.

Table I shows the results of our analysis on some oscillators. The ability to estimate the resonator merit factor is necessary to understand the oscillator inside. Experience indicates that the product $Q_0 Q$ is a technical constant of the piezoelectric quartz resonator, in the range from $1 \times 10^{13}$ to $2 \times 10^{13}$. As a matter of fact, the highest values are found in the 5 MHz resonators. In load conditions, the resonator merit factor is somewhat lower. The actual value depends on frequency, on the designer skill, and on the budget for implementation. A bunch of data are available from [1, 6, 43], and from our early attempts to measure the resonator frequency stability [4]. The oscillators we have analyzed exhibit the highest available stability, for we are confident about published data. The Agilent 10811 (hence the Agilent prototype) is closer to the routine production, and probably closer to the cost-performance tradeoff, as compared to the other ones, thus understanding oscillator the inside is more difficult. Nonetheless, in this case the value of $Q_x$ is so low that there is no doubt that it can not be the resonator merit factor.

In the case of the Oscilloquartz 8607 (Fig. 6), the $f^{-3}$ noise is too low for it to be extracted from the $S_\phi(f)$ spectrum available on data sheet, which starts from 1 Hz. Yet, we can use the device specifications $S_\phi(f)|_{1 \text{ Hz}} = −127 \text{ dBrad}^2/\text{Hz}$, $S_\phi(f)|_{10 \text{ Hz}} = −142 \text{ dBrad}^2/\text{Hz}$, and $S_\phi(f)|_{1 \text{ kHz}} = −153 \text{ dBrad}^2/\text{Hz}$. In fact, looking at the spectrum and at the Allan variance it is clear that at $f = 1$ Hz and $f = 10$ Hz the terms $b_{-3} f^{-3}$ and $b_{-1} f^{-1}$ determine $S_\phi(f)$, with at most a minor contribution of $b_0$. It is also clear that $S_\phi(f)|_{1 \text{ kHz}} \approx b_0$. Thus $b_{-3}$ and $b_{-1}$ are obtained by solving a system of two equations like $S_\phi(f) = b_{-3} f^{-3} + b_{-1} f^{-1} + b_0$, at 1 Hz and 10 Hz.

In the case of the Wenzel 501-04623 oscillator (Fig. 7), the specifications available on the manufacturer web site consist of a few points, while the whole spectrum is not published. Experience indicates that in the case of 100 MHz oscillators the $f^{-1}$ line tends to be hidden by the frequency flickering. That said, we can only guess that the $f^{-1}$ noise of the sustaining amplifier is similar to that of other oscillators. This is sufficient to estimate $f''_s$, and to notice that the merit factor $Q_s$ is far too low as compared to the state of the technology, and to conclude that the $f^{-3}$ phase noise is due to the fluctuation of the resonator natural frequency. It is to be remarked that the power at the amplifier input is of the order of $10$–$20 \mu \text{W}$ in all other cases, and of 1 mW here. In addition, the 100 MHz resonator is smaller in size than the other resonator. A relatively high frequency flicker is therefore not surprising.

The examples shown above indicate that, under the assumption of Sections III–IV, the oscillator frequency flickering is chiefly due to the fluctuation of the resonator natural frequency.
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[42] Candelier (unpublished), V. Candelier (CMAC), personal communication.